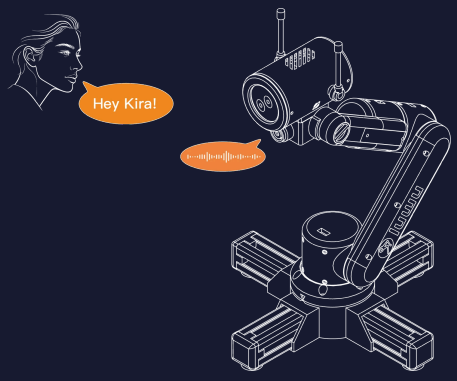
RIG-Arm · Kaka

Desktop Interactive Robotic Arm

Quick Start Guide

From algorithms to living entities · Start your desktop cyber evolution



Quick Start Guide

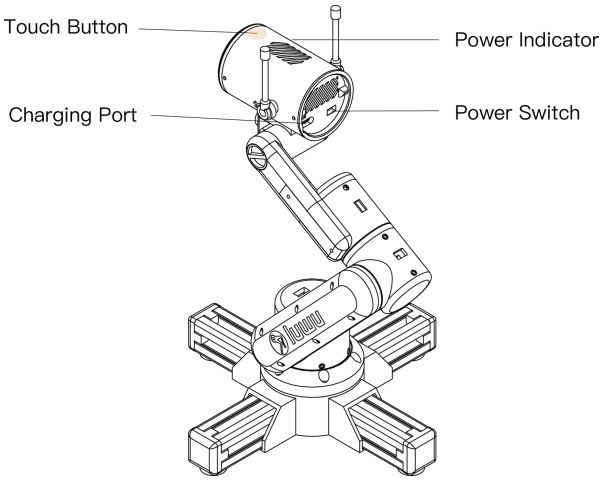
0 Disclaimer

Each electronic kit from our store is inspected for appearance and basic functionality before shipping. Please **power it on and test it as soon as you receive it** and confirm that it works properly before installing it onto the structure. Damage caused by installing without testing, or by improper installation or usage environment, is not covered by after-sales service.

1 Power On/Off & Charging

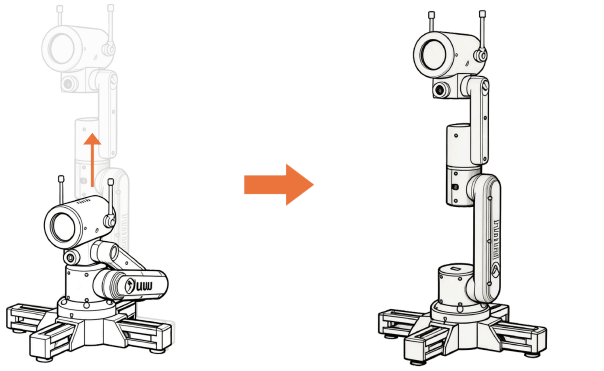
To ensure the best first experience, we recommend fully charging the battery first. During charging, you can check the battery level via the power indicator; when fully charged, the power indicator turns green.

Action	Function
Single tap	Touch button
Double tap	Control power indicator
Long press	Switch



2 Calibration Mode

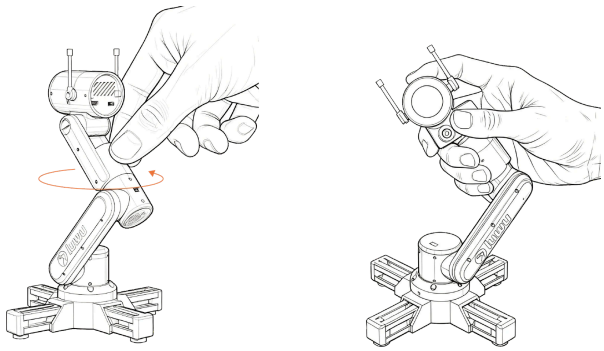
In daily use, long-press the touch button or say the voice command "Enter Calibration Mode / Exit Calibration Mode" to freely toggle calibration state. On first power-up, the kit enters calibration mode automatically and releases servo resistance; as shown, manually adjust all joints to the standard upright posture, then tap the touch button to save the mechanical zero point.



3 Teach Mode

RIG-Arm voice teach mode three steps:

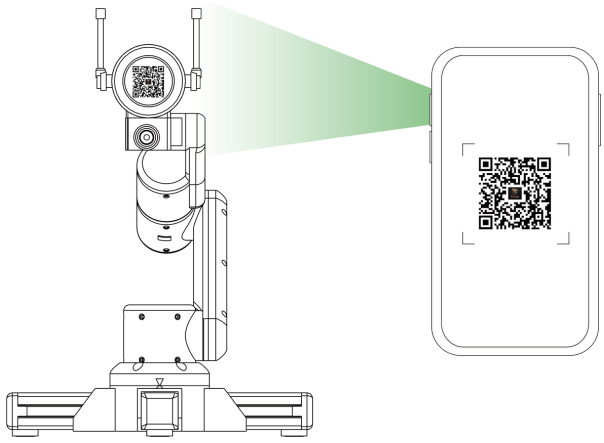
1. Say "Enter Teach Mode": the arm auto-homes, servos unlock, and you can drag joints to record motion (up to 15s per take, auto-exit on timeout);
2. Say "End Teach": the arm resets to the initial posture and the recorded track auto-saves;
3. Say "Replay Teach": replay the saved track, unlimited repeats.



4 Connect RIG-Arm

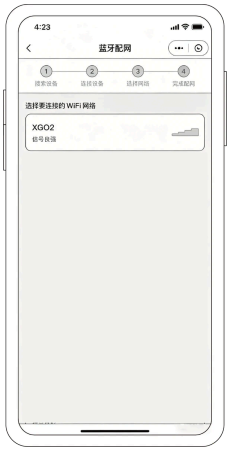
After power-up, follow the steps below to connect your RIG-Arm:

1. Download the Luwubot app: for iPhone, search for "Luwubot" in the App Store and install it; for Android, search for "Luwubot" in Google Play and install it.
2. Open the app and follow the in-app instructions to complete network pairing.
3. After pairing, the arm auto-stands upright; by default it sways slightly, use the voice commands "stop moving" or "be quiet" to stop it.



5 Select & Configure WiFi

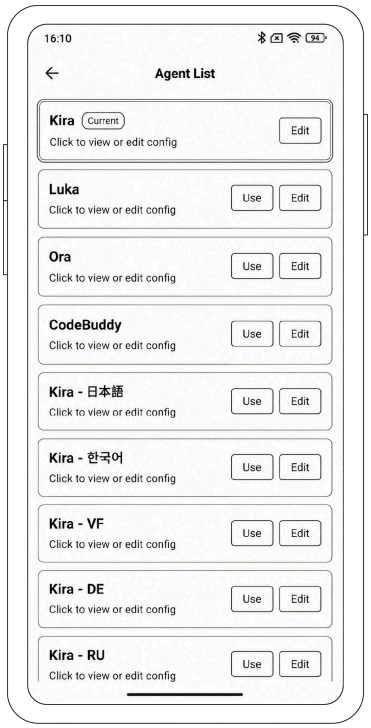
Select a 2.4G network from the WiFi list (note: 5G is not supported yet), manually enter the password and tap "Start Pairing".





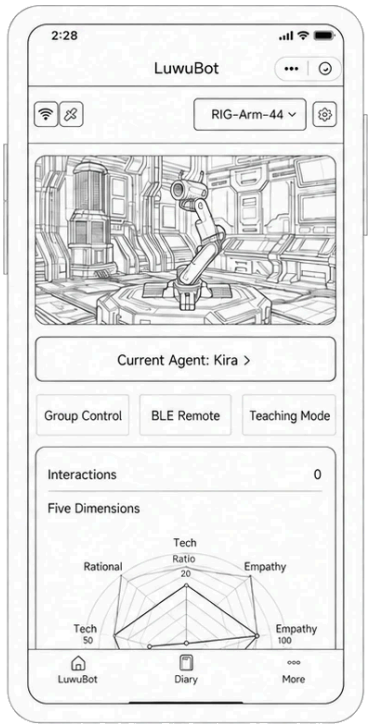
6 Cyber Soul Development

Connect your Kaka and witness its evolution from machine to "cyber life".



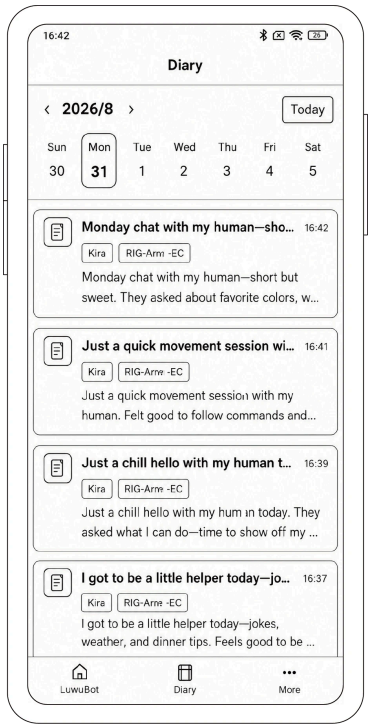
Agent Setup

Through the "Xiaolu Classmate" mini program, customize its personality, dialogue style and voice.



Mood & Growth

During daily interactions, view Kaka's "Five-Dimension Personality" panel to witness its evolution.



Mood Diary

It auto-generates an exclusive mood diary based on interaction frequency and content.

7 Interactive Commands

After boot and online, wake the robot with the wake word "Xiaolu Classmate". Try these command words!

Nod | Shy | Act Cute | Head Tilt | Bow | Stretch | Play Dead | Wag Tail | Apologize

Notice: Only in Teach/Calibration mode after servo torque-release are joints allowed to be adjusted manually.